

# MOHAMED SATHAK A.J. COLLEGE OF ENGINEERING

(Approved by AICTE, New Delhi and Affiliated to Anna University, Chennai)





# | Name of the Subject Code | ME3491 | ME3491 | Academic Year | 2022-2023 | Department of Mechanical Engineering | Dr.G.Ramesh | Theory of Machines | Name of the handling Faculty | Dr.G.Ramesh | Dr.G

## **Course Objective**

- To study the basic components of mechanisms, analyzing the assembly with respect to the displacement, velocity, and acceleration at any point in a link of a mechanism and design cam mechanisms for specified output motions.
- To study the basic concepts of toothed gearing and kinematics of gear trains
- To Analyzing the effects of friction in machine elements
- To Analyzing the force-motion relationship in components subjected to external forces and analyzing of standard mechanisms.
- To Analyzing the undesirable effects of unbalances resulting from prescribed motions in mechanism and the effect of dynamics of undesirable vibrations.

#### **Course Outcome**

### On completion of the course, the student is expected to be able to

CO1: Explain the basics of mechanism and sketch the camprofile

CO2: Solve problems on gears and gear trains.

CO3: Examine friction in machine elements.

CO4: Calculate static and dynamic forces of mechanisms.

CO5: Calculate the balancing masses and their locations of reciprocating and rotating masses. Computing the frequency of free vibration, forced vibration and damping coefficient.

#### Lesson Plan

CI		T / R*	Periods	Mode of				
Sl. No.	Topic(s)	Book	Require d	Teaching (BB / PPT / NPTEL / MOOC / etc )	Blooms Level (L1-L6)	CO	PO	
UNI	T I: KINEMATICS OF MECHANISMS							
1	Introduction to the subject, mechanisms and terminology	R3	1	BB	L1	CO1	PO1, PO12	
2	Four bar chain and inversion of four bar chain, Tranmission angle, mechanical advantage	R3	1	PPT/BB	L2	CO1	PO1, PO12	
3	Other inversion mechanisms, kinematic analysis in simple mechanisms	R3	1	PPT/BB	L2	CO1	PO1, PO12	
4	Velocity and acceleration polygons, Analytical method	R3	1	ВВ	L3	CO1	PO1, PO2, PO12	
5	Introduction to CAM, Classification, nomenclature	R3	1	BB	L2	CO1	PO1, PO12	
6	Different follower motion and Displacement diagrams	R3	1	BB	L2	CO1	PO1, PO12	
7	Problems in layout of cam profile	R3	1	BB	L3	CO1	PO1, PO2, PO12	
8	Problems in layout of cam profile	R3	1	BB	L3	CO1	PO1, PO2, PO12	
9	Circular and tangent cams description	R3	1	BB	L2	CO1	PO1, PO2, PO12	

Suggested Activity: Assignment / Case Studies / Tutorials/ Quiz / Mini Projects / Model Developed/others Planned if any.

**Evaluation method: Tutorials** 

UNI	T II: GEARS AND GEAR TRAINS						
10	Introduction to gears, Law gearing and gear profiles	R3	1	PPT/BB	L1	CO2	PO1, PO12
11	Spur Gear terminology, definitions, Length of path of contact and contact ratio, Interference and under	R3	1	PPT/BB	L1	CO2	PO1, PO12
12	Problems on finding the length of path of contact arc of contact, contact ratio	R3	1	BB	L3	CO2	PO1, PO2, PO12
13	Problems on finding the length of path of contact arc of contact, contact ratio	R3	1	ВВ	L3	CO2	PO1, PO2, PO12
14	Problems on finding the minimum number of teeth on gears to avoid interference	R3	1	BB	L3	CO2	PO1, PO2, PO12
15	Introduction to gear train, types, speed ratio, train value and epicyclic gear train.	R3	1	BB	L2	CO2	PO1, PO2, PO12
16	Epicyclic Gear Trains and related problems	R3	1	BB	L3	CO2	PO1, PO2, PO12
17	Epicyclic Gear Trains and related problems	R3	1	BB	L3	CO2	PO1, PO2, PO12
18	Automotive tranmission gear trains	R3	1	PPT/BB	L2	CO2	PO1, PO2, PO12

Suggested Activity: Assignment / Case Studies / Tutorials/ Quiz / Mini Projects / Model Developed/others Planned if any

**Evaluation method: Tutorials** 

# UNIT III: FRICTION IN MACHINE ELEMENTS

19	Laws of friction, limiting friction, static and kinetic friction, angle of friction	R3	1	PPT/BB	L2	СОЗ	PO1, PO12
20	Friction in screw threads, principle of operation of screw jack (inclined plane analogy), efficiency of and	R3	1	PPT/BB	L2	СОЗ	PO1, PO12
21	Problems on screw jacks	R3	1	BB	L3	СОЗ	PO1, PO2, PO12
22	Friction clutches and Belt and rope drives	R3	1	PPT/BB	L2	СОЗ	PO1, PO2, PO12
23	Problems on clutch and belt drives	R3	1	ВВ	L3	СОЗ	PO1, PO2, PO12
24	Problems on clutch and belt drives	R3	1	BB	L3	СОЗ	PO1, PO2, PO12
25	Friction in brakes, Band and Block brakes and related problems	R3	1	PPT/BB	L3	СОЗ	PO1, PO2, PO12
26	Problems in brakes	R3	1	BB	L3	СОЗ	PO1, PO2, PO12
27	Bearings and lubrication.	R3	1	BB	L2	СОЗ	PO1, PO2, PO12

Suggested Activity: Assignment / Case Studies / Tutorials/ Quiz / Mini Projects / Model Developed/others Planned if any

**Evaluation method: Assignment** 

# UNIT IV: FORCE ANALYSIS

28	Introduction to force analysis, appplied and constrained forces	R3	1	BB	L2	CO4	PO1, PO12
29	Free body diagrams, Static and dynamic equilibrium	R3	1	BB	L2	CO4	PO1, PO2, PO12
30	Equilibrium of Two, Three and four force members	R3	1	ВВ	L2	CO4	PO1, PO2, PO12
31	Static force analysis in simple machine members, superposition principle	R3	1	BB	L2	CO4	PO1, PO2, PO12
32	Static force analysis in simple machine members	R3	1	BB	L3	CO4	PO1, PO2, PO12

33	Dynamic force analysis, inertia force and inertia torque	R3	1	ВВ	L2	CO4	PO1, PO2, PO12
34	D'Alembert's principle, equivalent offset inertia force	R3	1	BB	L2	CO4	PO1, PO12
35	Dynamic force analysis in simple machine members, superposition principle	R3	1	BB	L3	CO4	PO1, PO2, PO12
36	Dynamic force analysis in simple machine members	R3	1	BB	L3	CO4	PO1, PO2, PO12
Sugg	ested Activity: Assignment / Case Studies / Tutorials/	Quiz / Mini I	Projects / M	odel Developed	others Plann	ed if any	
Evalu	nation method: Students Seminar						
UNI	T V: BALANCING AND VIBRATION						
37	Introduction to balancing, Static and dynamic balancing	R3	1	BB	L2	CO5	PO1, PO12
38	Balancing of rotating masses in different planes	R3	1	BB	L2	CO5	PO1, PO12
39	Problems solving in Balancing of revolving masses	R3	1	BB	L3	CO5	PO1, PO2, PO12
40	Balancing of reciprocating mass, force balancing of locomotives and problems	R3	1	ВВ	L3	CO5	PO1, PO2, PO12
41	Introduction to vibration, free vibrations and types	R3	1	BB	L2	CO5	PO1, PO12
42	Equation of motion for natural frequency, damped vibration	R3	1	BB	L2	CO5	PO1, PO2, PO12
43	Transverse vibration, critical speed of simple shaft	R3	1	BB	L2	CO5	PO1, PO2, PO12
44	Torsional vibration, forced vibration, vibration isolation	R3	1	ВВ	L3	CO5	PO1, PO2, PO12
45	Gyroscope concepts.	R3	1	BB	L2	CO5	PO1, PO12
Evalı	ested Activity: Assignment / Case Studies / Tutorials/ nation method: Seminar	Quiz / Mini I	Projects / M	odel Developed	others Plann/	ed if any	
	ent Beyond the Syllabus Planned						
1	Concept of flywheel						

# **Text Books**

- 1 Uicker, J.J., Pennock G.R and Shigley, J.E., "Theory of Machines and Mechanisms", Oxford University Press, 2017.
- 2 Ramamurthi. V, "Mechanics of Machines", Narosa Publishing House, 3rd edition 2019

## **Reference Books**

- 1 AmitabhaGhosh and Asok Kumar Mallik, "Theory of Mechanisms and Machines", Affiliated East-West Pvt. Ltd., 1988.
- 2 Rao.J.S. and Dukkipati.R.V. "Mechanism and Machine Theory", New Age International Pvt. Ltd., 2nd edition, 2014.
- 3 Rattan, S.S, "Theory of Machines", McGraw-Hill Education Pvt. Ltd., 5th edition 2019.
- 4 Robert L. Norton, Kinematics and Dynamics of Machinery, Tata McGraw-Hill, 2013.
- 5 Wilson and Sadler, Kinematics and Dynamics of Machinery, Pearson, 2008.

## Website / URL References

- 1 <u>https://nptel.ac.in/courses/112/106/112106270/</u>
- 2 https://nptel.ac.in/courses/112/104/112104121/
- 3 https://nptel.ac.in/courses/112/105/112105268/

						Bloom	s Level							
Level	1 (L1):	Rememb	ering		Lower	Fixed	Level 4	( <b>L4</b> ) : A	Analyzi	ng				Projects /
Level	2 (L2):	Understa	nding		Order			5 (L5) : I		_			r Order nking	Mini
Level	3 (L3):	Applying	•		Thinking	Exams	Level 6	(L6) : (	Creatin	g			8	Projects
			Мар	ping syl	labus wit	h Bloo	m's Ta	xonom	y LOT	and H	ОТ			
Ur	nit No		Unit	Name		L1	L2	L3	L4	L5	L6	LOT	НОТ	Total
ι	Unit 1 KINEMATICS OF MECHANISMS			S	1	5	3	0	0	0	9	0	9	
τ	Unit 2 GEARS AND GEAR TRAINS				2	2	5	0	0	0	9	0	9	
ι	Jnit 3	FRICTIO	N IN MAC	HINE ELE	MENTS	0	4	5	0	0	0	9	0	9
ι	Jnit 4	FORCE A	NALYSIS			0	6	3	0	0	0	9	0	9
Į	Jnit 5	BALANC	ING AND	VIBRATIO	ON	0	6	3	0	0	0	9	0	9
			Total			3	23	19	0	0	0	45	0	45
Total Percentage					6.6667	51.111	42.222	0	0	0	100	0	100	
				<u> </u>		CO PO	Mappin:	g				<u> </u>		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO 12	PSO1	PSO2
CO1	3	2	2		2			1				1	3	1
CO2	3	2	2		2			1				1	3	1
CO3	3	2	2		2			1				1	3	1
CO4	3	2	2		2			1				1	3	1
CO5	3	2	2		2			1				1	3	1
Avg	3	2	2		2			1				1	3	1
					Justifica	ation for	СО-РО	mapping	g					
CO1	effectively Importance	PO3: A one given to	considerabl follow ethic	e impact is es during th	ore predoming given to the design proof ore predoming	complex ocess, PO	problen 12: Conc	ns. PO5: Nepts help	Modern t s in life l	ools used	d whre ev	er need	led. PO8	i:
CO2	effectively Importanc	PO3: A one given to a	considerabl follow ethic	e impact is s during th	given to the design pro	complex ocess, PO	problen 12: Conc	ns. PO5: Nepts help	Modern t s in life l	ools used long leari	d whre ev ning	er need	led. PO8	i:
CO3	effectively Importanc	PO3: A one given to	considerabl follow ethic	e impact is s during th	given to the design pro	complex ocess, PO	problen 12: Conc	ns. PO5: I cepts help	Modern t s in life l	ools used	d whre ev	er need	led. PO8	d:
CO4	effectively Importance	PO3: A one given to	considerabl follow ethic	e impact is s during th	given to the design pro	complex ocess, PO	problen 12: Conc	ns. PO5: I cepts help	Modern t s in life l	ools used	d whre ev	er need	led. PO8	d:
CO5	effectively	, PO3: A	considerabl	e impact is	ore predoming given to the design pro	complex	problen	ns. PO5: 1	Modern t	ools used	d whre ev			
	3		High level		2		Mo	oderate le	evel		1		Low lo	evel
Name	& Sign o	of Faculty	In charge	: Dr. Ram	nesh G									
Name	& Sign o	of Subject	Expert :	Dr. Rame	sh G									
Head	of the De	partment	:	Dr. Shun	mugasunda	ram M								

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